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Subhasis Chaudhuri A.N. Rajagopalan

Depth From Defocus A Real Aperture Imaging Approach

Aleš Leonardis, Horst Bischof, Axel Pinz

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Depth From Defocus: A Real Aperture Imaging Approach Subhasis Chaudhuri, A.N. Rajagopalan, 2012-12-06 Computer vision is becoming increasingly important in several industrial applications such as automated inspection robotic manipulations and autonomous vehicle guidance These tasks are performed in a 3 D world and it is imperative to gather reliable information on the 3 D structure of the scene This book is about passive techniques for depth recovery where the scene is illuminated only by natural light as opposed to active methods where a special lighting device is used for scene illumination Passive methods have a wider range of applicability and also correspond to the way humans infer 3 D structure Computer Vision -- ECCV 2006 Aleš Leonardis, Horst Bischof, Axel Pinz, 2006-07-25 The four volume from visual images set comprising LNCS volumes 3951 3952 3953 3954 constitutes the refereed proceedings of the 9th European Conference on Computer Vision ECCV 2006 held in Graz Austria in May 2006 The 192 revised papers presented were carefully reviewed and selected from a total of 811 papers submitted The four books cover the entire range of current issues in computer vision The papers are organized in topical sections on recognition statistical models and visual learning 3D reconstruction and multi view geometry energy minimization tracking and motion segmentation shape from X visual tracking face detection and recognition illumination and reflectance modeling and low level vision segmentation and grouping ECCV 2012 Andrew Fitzgibbon, Svetlana Lazebnik, Pietro Perona, Yoichi Sato, Cordelia Schmid, 2012-09-26 The seven volume set comprising LNCS volumes 7572 7578 constitutes the refereed proceedings of the 12th European Conference on Computer Vision ECCV 2012 held in Florence Italy in October 2012 The 408 revised papers presented were carefully reviewed and selected from 1437 submissions The papers are organized in topical sections on geometry 2D and 3D shapes 3D reconstruction visual recognition and classification visual features and image matching visual monitoring action and activities models optimisation learning visual tracking and image registration photometry lighting and colour and image segmentation Pattern Recognition Xiaoyi Jiang, Joachim Hornegger, Reinhard Koch, 2014-10-14 This book constitutes the refereed proceedings of the 36th German Conference on Pattern Recognition GCPR 2014 held in M nster Germany in September 2014 The 58 revised full papers and 8 short papers were carefully reviewed and selected from 153 submissions The papers are organized in topical sections on variational models for depth and flow reconstruction bio informatics deep learning and segmentation feature computation video interpretation segmentation and labeling image processing and analysis human pose and people tracking interpolation and inpainting Pattern Recognition Katrin Franke, Klaus-Robert Müller, Bertram Nickolay, Ralf Schäfer, 2006-09-21 This book constitutes the refereed proceedings of the 28th Symposium of the German Association for Pattern Recognition DAGM 2006 The book presents 32 revised full papers and 44 revised poster papers together with 5 invited papers Topical sections include image filtering restoration and segmentation shape analysis and representation recognition categorization and detection computer vision and image retrieval machine learning and

statistical data analysis biomedical data analysis and more Pattern Recognition Joachim Denzler, Gunther Notni, Herbert Süße, 2009-09-02 This book constitutes the refereed proceedings of the 31st Symposium of the German Association for Pattern Recognition DAGM 2009 held in Jena Germany in September 2009 The 56 revised full papers were carefully reviewed and selected from numerous submissions. The papers are organized in topical sections on motion and tracking pedestrian recognition and automotive applications features single view and 3D reconstruction learning and classification pattern recognition and estimation stereo and multi-view reconstruction image analysis and applications and Pattern Recognition Gunther Notni, 2009-09-03 This book constitutes the refereed proceedings of the 31st Symposium of the German Association for Pattern Recognition DAGM 2009 held in Jena Germany in September 2009 The 56 revised full papers were carefully reviewed and selected from numerous submissions. The papers are organized in topical sections on motion and tracking pedestrian recognition and automotive applications features single view and 3D reconstruction learning and classification pattern recognition and estimation stereo and multi view reconstruction image analysis and applications and segmentation Computer Vision - ECCV 2004 Tomas Pajdla, Jiri Matas, 2004-04-28 The four volume set comprising LNCS volumes 3021 3022 3023 3024 constitutes the refereed proceedings of the 8th European Conference on Computer Vision ECCV 2004 held in Prague Czech Republic in May 2004 The 190 revised papers presented were carefully reviewed and selected from a total of 555 papers submitted. 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Symposium, Allan Hanbury, 2005-08-18 This book constitutes the refereed proceedings of the 27th Symposium of the German Association for Pattern Recognition DAGM 2005 held in Wien Austria in August September 2005 The 29 revised full papers and 31 revised poster papers presented together with 2 invited papers were carefully reviewed and selected from 122 submissions. The papers are organized in topical sections on color analysis stereo vision invited paper segmentation and grouping automatic speech understanding 3D view registration and surface modeling motion and tracking computational learning applications and uncertainty and robustness Advances in Multimedia Modeling Tat-Jen Cham, Jianfei Cai, Chitra Dorai, Deepu Rajan, Tat-Seng Chua, Liang-Tien Chia, 2007-07-05 The two volume set LNCS 4351 and LNCS 4352 constitutes the refereed proceedings of the 13th International Multimedia Modeling Conference MMM 2007 held in Singapore in January 2007 Based on rigorous reviewing the program committee selected 123 carefully revised full papers of the main technical sessions and 33 revised full papers of four special sessions from a total of 392 submissions for presentation in two volumes **Computer Vision - ECCV 2016** Bastian Leibe, Jiri Matas, Nicu Sebe, Max Welling, 2016-09-15 The eight volume set comprising LNCS volumes 9905 9912 constitutes the refereed proceedings of the 14th European Conference on Computer Vision ECCV 2016 held in Amsterdam The Netherlands in October 2016 The 415 revised papers presented were carefully reviewed and selected from 1480 submissions. The papers cover all aspects of computer vision and pattern recognition such as 3D computer vision computational photography sensing and display face and gesture low level vision and image processing motion and tracking optimization methods physics based vision photometry and shape from X recognition detection categorization indexing matching segmentation grouping and shape representation statistical methods and learning video events activities and surveillance applications. They are organized in topical sections on detection recognition and retrieval scene understanding optimization image and video processing learning action activity and tracking 3D and 9 poster sessions Computer Vision - ACCV 2007 Yasushi Yagi, Sing Bing Kang, In So Kweon, Hongbin Zha, 2007-11-14 This title is part of a two volume set that constitutes the refereed proceedings of the 8th Asian Conference on Computer Vision ACCV 2007 Coverage includes shape and texture image and video processing face and

gesture tracking camera networks learning motion and tracking retrieval and search human pose estimation matching face gesture action detection and recognition low level vision and phtometory motion and tracking human detection and Blind Image Deconvolution Subhasis Chaudhuri, Rajbabu Velmurugan, Renu Rameshan, 2014-09-22 Blind deconvolution is a classical image processing problem which has been investigated by a large number of researchers over the last four decades The purpose of this monograph is not to propose yet another method for blind image restoration Rather the basic issue of deconvolvability has been explored from a theoretical view point Some authors claim very good results while quite a few claim that blind restoration does not work The authors clearly detail when such methods are expected to work and when they will not In order to avoid the assumptions needed for convergence analysis in the Fourier domain the authors use a general method of convergence analysis used for alternate minimization based on three point and four point properties of the points in the image space The authors prove that all points in the image space satisfy the three point property and also derive the conditions under which four point property is satisfied This provides the conditions under which alternate minimization for blind deconvolution converges with a quadratic prior Since the convergence properties depend on the chosen priors one should design priors that avoid trivial solutions Hence a sparsity based solution is also provided for blind deconvolution by using image priors having a cost that increases with the amount of blur which is another way to prevent trivial solutions in joint estimation This book will be a highly useful resource to the researchers and academicians in the specific area of blind deconvolution **3-D Shape Estimation and Image Restoration** Paolo Favaro, Stefano Soatto, 2007-03-12 Images contain information about the spatial properties of the scene they depict When coupled with suitable assumptions images can be used to infer thr dimensional information For instance if the scene contains objects made with homogeneous material such as marble variations in image intensity can be sociated with variations in shape and hence the shading in the image can be exploited to infer the shape of the scene shape from shading Similarly if the scene contains statistically regular structures variations in image intensity can be used to infer shape from textures Shading texture cast shadows cluding boundaries are all cues that can be exploited to infer spatial properties of the scene from a single image when the underlying assumptions are sat ed In addition one can obtain spatial cues from multiple images of the same scene taken with changing conditions For instance changes in the image due to a moving light source are used in photometric stereo changes in the image due to changes in the position of the cameras are used in stereo structure from motion and motion blur Finally changes in the image due to changes in the geometry of the camera are used in shape from defocus In this book we will concentrate on the latter two approaches motion blur and defocus which are referred to collectively as accommodation cues Motion Deblurring A. N. Rajagopalan, Rama Chellappa, 2014-05-08 Comprehensive guide to the restoration of images degraded by motion blur encompassing algorithms and architectures with novel computational photography methods Motion-Free Super-Resolution Subhasis Chaudhuri, Joshi Manjunath, 2006-06-20

Motion Free Super Resolution is a compilation of very recent work on various methods of generating super resolution SR images from a set of low resolution images The current literature on this topic deals primarily with the use of motion cues for the purpose of generating SR images These cues have it is shown their advantages and disadvantages In contrast this book shows that cues other than motion can also be used for the same purpose and addresses both the merits and demerits of these new techniques Motion Free Super Resolution supersedes much of the lead author's previous edited volume Super Resolution Imaging and includes an up to date account of the latest research efforts in this fast moving field This sequel also features a style of presentation closer to that of a textbook with an emphasis on teaching and explanation rather than scholarly presentation **Computer Vision** Richard Szeliski, 2022-01-03 Computer Vision Algorithms and Applications explores the variety of techniques used to analyze and interpret images It also describes challenging real world applications where vision is being successfully used both in specialized applications such as image search and autonomous navigation as well as for fun consumer level tasks that students can apply to their own personal photos and videos More than just a source of recipes this exceptionally authoritative and comprehensive textbook reference takes a scientific approach to the formulation of computer vision problems These problems are then analyzed using the latest classical and deep learning models and solved using rigorous engineering principles Topics and features Structured to support active curricula and project oriented courses with tips in the Introduction for using the book in a variety of customized courses Incorporates totally new material on deep learning and applications such as mobile computational photography autonomous navigation and augmented reality Presents exercises at the end of each chapter with a heavy emphasis on testing algorithms and containing numerous suggestions for small mid term projects Includes 1 500 new citations and 200 new figures that cover the tremendous developments from the last decade Provides additional material and more detailed mathematical topics in the Appendices which cover linear algebra numerical techniques estimation theory datasets and software Suitable for an upper level undergraduate or graduate level course in computer science or engineering this textbook focuses on basic techniques that work under real world conditions and encourages students to push their creative boundaries Its design and exposition also make it eminently suitable as a unique reference to the fundamental techniques and current research literature in computer vision Mathematical Foundations of Image Processing and Analysis, Volume 2 Jean-Charles Pinoli, 2014-07-22 Mathematical Imaging is currently a rapidly growing field in applied mathematics with an increasing need for theoretical mathematics This book the second of two volumes emphasizes the role of mathematics as a rigorous basis for imaging sciences It provides a comprehensive and convenient overview of the key mathematical concepts notions tools and frameworks involved in the various fields of gray tone and binary image processing and analysis by proposing a large but coherent set of symbols and notations a complete list of subjects and a detailed bibliography It establishes a bridge between the pure and applied mathematical disciplines and the processing and analysis of gray tone and binary images It is accessible to readers who have neither extensive mathematical training nor peer knowledge in Image Processing and Analysis It is a self contained book focusing on the mathematical notions concepts operations structures and frameworks that are beyond or involved in Image Processing and Analysis The notations are simplified as far as possible in order to be more explicative and consistent throughout the book and the mathematical aspects are systematically discussed in the image processing and analysis context through practical examples or concrete illustrations Conversely the discussed applicative issues allow the role of mathematics to be highlighted Written for a broad audience students mathematicians image processing and analysis specialists as well as other scientists and practitioners the author hopes that readers will find their own way of using the book thus providing a mathematical companion that can help mathematicians become more familiar with image processing and analysis and likewise image processing and image analysis scientists researchers and engineers gain a deeper understanding of mathematical notions and concepts

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