

1994 IEEE Symposium On Autonomous Underwater Vehicle Technology



Autonomous Underwater Vehicle Technology  
Proceedings Of The Auv Symposium On 19 20 July 1994  
Cambridge Massachusetts

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*Proceedings of the Technology and the Mine Problem Symposium* Albert M. Bottoms, Barbara Honegger, 1996

**Proceedings of the ... International Symposium on Underwater Technology**, 1998 *Undersea Vehicles and National Needs* National Research Council, Division on Engineering and Physical Sciences, Commission on Engineering and Technical Systems, Committee on Undersea Vehicles and National Needs, 1996-11-19 The United States faces decisions requiring information about the oceans in vastly expanded scales of time and space and from oceanic sectors not accessible with the suite of tools now used by scientists and engineers Advances in guidance and control communications sensors and other technologies for undersea vehicles can provide an opportunity to understand the oceans influence on the energy and chemical balance that sustains humankind and to manage and deliver resources from and beneath the sea This book assesses the state of undersea vehicle technology and opportunities for vehicle applications in science and industry It provides guidance about vehicle subsystem development priorities and describes how national research can be focused most effectively *Proceedings of the 9th International Symposium on Unmanned Untethered Submersible Technology*, September 27-29, 1995, 1995

*Proceedings of 1995 IEEE International Conference on Robotics and Automation*, May 21-27, 1995, Nagoya, Aichi, Japan IEEE Robotics and Automation Society, 1995 **Advances and Applications in Sliding Mode Control systems** Ahmad Taher Azar, Quanmin Zhu, 2014-11-01 This book describes the advances and applications in Sliding mode control SMC which is widely used as a powerful method to tackle uncertain nonlinear systems The book is organized into 21 chapters which have been organised by the editors to reflect the various themes of sliding mode control The book provides the reader with a broad range of material from first principles up to the current state of the art in the area of SMC and observation presented in a clear matter of fact style As such it is appropriate for graduate students with a basic knowledge of classical control theory and some knowledge of state space methods and nonlinear systems The resulting design procedures are emphasized using Matlab Simulink software **Proceedings of the ... Winter Simulation Conference**, 1997

**Proceedings of NOISE-CON ...**, 1996 *Essentials of Machine Olfaction and Taste* Takamichi Nakamoto, 2016-04-18 *Essentials of Machine Olfaction and Taste* This book provides a valuable information source for olfaction and taste which includes a comprehensive and timely overview of the current state of knowledge of use for olfaction and taste machines Presents original latest research in the field with an emphasis on the recent development of human interfacing Covers the full range of artificial chemical senses including olfaction and taste from basic through to advanced level Timely project in that mobile robots olfactory displays and odour recorders are currently under research driven by commercial demand **Oceans '96 MTS/IEEE**, 1996 **Oceans '97 MTS/IEEE**, 1997 **From Animals to Animats 4** Pattie Maes, 1996 *From Animals to Animats 4* brings together the latest research at the frontier of an exciting new approach

to understanding intelligence      Tastes & Aromas Graham A. Bell, Annesley J. Watson, 1999 Provides an overview of the current status of basic science on the senses of smell taste and pungency on which practical applications are based and then show where some of the most interesting practical outcomes of these fundamentals are currently being applied      1995  
*American Control Conference* American Automatic Control Council, 1995      **Proceedings of the 1994 Symposium on Autonomous Underwater Vehicle Technology** ,1994-01-01      **Underwater Technology** ,1998      **Proceedings of the IEEE International Symposium on Industrial Electronics** ,1997      *Sea Technology* ,1994      **AUV '94** Symposium on Autonomous Underwater Vehicle Technology, 1994      Oceans '95 ,1995

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