
AUTONOMOUS, MODEL-BASED DIAGNOSIS AGENTS

Michael Schroeder

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Autonomous Model Based Diagnosis Agents

**James L. Rash, Christopher A.
Rouff, Walter Truszkowski, Diana
Gordon, Michael G. Hinchey**



Autonomous Model Based Diagnosis Agents:

Autonomous, Model-Based Diagnosis Agents Michael Schroeder, 2012-12-06 Autonomous Model Based Diagnosis Agents defines and describes the implementation of an architecture for autonomous model based diagnosis agents. It does this by developing a logic programming approach for model based diagnosis and introducing strategies to deal with more complex diagnosis problems and then embedding the diagnosis framework into the agent architecture of vivid agents. Autonomous Model Based Diagnosis Agents surveys extended logic programming and shows how this expressive language is used to model diagnosis problems stemming from applications such as digital circuits, traffic control, integrity checking of a chemical database, alarm correlation in cellular phone networks, diagnosis of an automatic mirror furnace, and diagnosis of communication protocols. The book reviews a bottom up algorithm to remove contradiction from extended logic programs and substantially improves it by top down evaluation of extended logic programs. Both algorithms are evaluated in the circuit domain including some of the ISCAS85 benchmark circuits. This comprehensive in depth study of concepts, architectures, and implementation of autonomous model based diagnosis agents will be of great value for researchers, engineers, and graduate students with a background in artificial intelligence. For practitioners, it provides three main contributions: first, it provides many examples from diverse areas such as alarm correlation in phone networks to inconsistency checking in databases; second, it describes an architecture to develop agents; and third, it describes a sophisticated and declarative implementation of the concepts and architectures introduced.

Autonomous, Model-Based Diagnosis Agents Michael Schroeder, 1998-03-31 Autonomous Model Based Diagnosis Agents defines and describes the implementation of an architecture for autonomous model based diagnosis agents. It does this by developing a logic programming approach for model based diagnosis and introducing strategies to deal with more complex diagnosis problems and then embedding the diagnosis framework into the agent architecture of vivid agents. Autonomous Model Based Diagnosis Agents surveys extended logic programming and shows how this expressive language is used to model diagnosis problems stemming from applications such as digital circuits, traffic control, integrity checking of a chemical database, alarm correlation in cellular phone networks, diagnosis of an automatic mirror furnace, and diagnosis of communication protocols. The book reviews a bottom up algorithm to remove contradiction from extended logic programs and substantially improves it by top down evaluation of extended logic programs. Both algorithms are evaluated in the circuit domain including some of the ISCAS85 benchmark circuits. This comprehensive in depth study of concepts, architectures, and implementation of autonomous model based diagnosis agents will be of great value for researchers, engineers, and graduate students with a background in artificial intelligence. For practitioners, it provides three main contributions: first, it provides many examples from diverse areas such as alarm correlation in phone networks to inconsistency checking in databases; second, it describes an architecture to develop agents; and third, it describes a sophisticated and declarative implementation of the concepts and architectures introduced.

Autonomous Agents George A. Bekey, 2012-12-06 An agent is a system capable of perceiving the environment reasoning with the percepts and then acting upon the world Agents can be purely software systems in which case their percepts and output actions are encoded binary strings However agents can also be realized in hardware and then they are robots The Artificial Intelligence community frequently views robots as embodied intelligent agents The First International Conference on Autonomous Agents was held in Santa Monica California in February 1997 This conference brought together researchers from around the world with interests in agents whether implemented purely in software or in hardware The conference featured such topics as intelligent software agents agents in virtual environments agents in the entertainment industry and robotic agents Papers on robotic agents were selected for this volume Autonomous Agents will be of interest to researchers and students in the area of artificial intelligence and robotics

Software Engineering for Multi-Agent Systems V

Ricardo Choren, Alessandro Garcia, Carlos Lucena, Alexander Romanovsky, 2007-08-22 The papers selected for this volume present advances in software engineering approaches to develop dependable high quality multi agent systems These papers describe experiences and techniques associated with large multi agent systems in a wide variety of problem domains They cover fault tolerance exception handling and diagnosis security and trust verification and validation as well as early development phases and software reuse

Knowledge and Technology Integration in Production and Services

Vladimír Marík, Luis M. Camarinha-Matos, Hamideh Afsarmanesh, 2013-06-05 Knowledge and Technology Integration in Production and Services presents novel application scenarios for balanced distributed and integrated systems based on knowledge and up to date technology and provides a great opportunity for discussion of concepts models methodologies technological developments case studies new research ideas and other results among specialists It comprises the proceedings of the Fifth International Conference on Information Technology for BALANCED AUTOMATION SYSTEMS in Manufacturing and Services BASYS 02 which was sponsored by the International Federation for Information Processing IFIP and held in September 2002 in Cancun Mexico

Tools and Algorithms for the Construction and Analysis of Systems

Joost-Pieter Katoen, Perdita Stevens, 2002-03-20 ETAPS 2002 was the fth instance of the European Joint Conferences on Theory and Practice of Software ETAPS is an annual federated conference that was established in 1998 by combining a number of existing and new conferences This year it comprised 5 conferences FOSSACS FASE ESOP CC TACAS 13 satellite workshops ACL2 AGT CMCS COCV DCC INT LDTA SC SFEDL SLAP SPIN TPTS and VISS 8 invited lectures not including those specific to the satellite events and several tutorials The events that comprise ETAPS address various aspects of the system development process including specification design implementation analysis and improvement The languages methodologies and tools which support these activities are all well within its scope Different blends of theory and practice are represented with an inclination towards theory with a practical motivation on one hand and soundly based practice on the other Many of the issues involved in software design apply to systems in general including hardware systems and the emphasis on software is

not intended to be exclusive

Multi-Agent Systems and Applications IV Michal Pechoucek, Paolo Petta, Laszlo Zsolt Varga, 2005-10-03 The aim of the CEEMAS conference series is to provide a biennial forum for the presentation of multi agent research and development results With its particular geographical orientation towards Central and Eastern Europe CEEMAS has become an internationally recognised event with participants from all over the world After the successful CEEMAS conferences in St Petersburg 1999 Cracow 2001 and Prague 2003 the 2005 CEEMAS conference takes place in Budapest The programme committee of the conference series consists of established researchers from the region and renowned international colleagues showing the prominent rank of CEEMAS among the leading events in multi agent systems In the very competitive field of agent oriented conferences and workshops nowadays such as AAMAS, WIIAT, EUMAS, CIA, MATES the special profile of CEEMAS is that it is trying to bridge the gap between applied research achievements and theoretical research activities Our ambition is to provide a forum for presenting theoretical research with an evident application potential implemented application prototypes and their properties as well as industrial case studies of successful but also unsuccessful agent technology deployments This is why the CEEMAS proceedings volume provides a collection of research and application papers The technical research paper section of the proceedings see pages 11-499 contains pure research papers as well as research results in application settings while the application papers section see pages 500-530 contains papers focused on application aspects The goal is to demonstrate the real life value and commercial reality of multi agent systems as well as to foster communication between academia and industry in this field

Multiagent System Technologies Paolo Petta, Jörg Müller, Matthias Klusch, Michael Georgeff, 2007-09-19 This book constitutes the refereed proceedings of the 5th German Conference on Multiagent Systems Technologies MATES 2007 held in Leipzig Germany September 2007 co located with NetObjectDays, NODE 2007 The papers are organized in topical sections on engineering multi agent systems multi agent planning and learning multi agent communication interaction and coordination multi agent resource allocation multi agent planning and simulation as well as trust and reputation

Formal Approaches to Agent-Based Systems James L. Rash, Christopher A. Rouff, Walter Truszkowski, Diana Gordon, Michael G. Hinchey, 2003-06-29 This book constitutes the thoroughly refereed post proceedings of the First International Workshop on Formal Approaches to Agent Based Systems FAABS 2000 held in Greenbelt MD USA in April 2000 The 22 revised full papers presented together with 13 posters and two panel discussion reports were carefully reviewed and improved for inclusion in the book The papers are organized in topical sections on verifying agents mental states synthesizing agents initially frameworks and formalizations modeling and execution inter agent communication and adaptive agents

Research and Development in Intelligent Systems XXIV Max Bramer, Frans Coenen, Miltos Petridis, 2007-12-03 An agent in a multi agent system MAS has to generate plans for its individual goal but these plans may conflict with those that are already being scheduled or executed by other agents It must also be able to complete its planning and resolution of these conflicts within a reasonable time to have

an acceptable quality plan Although we adopt hierarchical planning HP for example see 7 12 using the decision theoretic planning DTP approach 6 for efficient planning it is not trivial to apply HPO to MAS In HP appropriate abstract plans are selected level by level to maximize the utility $U(p)$ where p is the expected plan comprising a sequence of primitive actions However in the MAS context conflicts between agents affect the efficiency and quality of resulting plans When a conflict is found at lower levels an additional sophisticated process for avoiding it conflict resolution must be invoked and some extra actions such as waiting for synchronization and detouring may have to be added to the plan The conflict resolution process may become costly or fail Even a single conflict if it is difficult to resolve will result in a plan with considerably lower quality than it otherwise would have As a result in multi agent systems the second or third best plans may result in better overall performance

Computational Logic in Multi-Agent Systems Joao Leite, Paolo Torroni, Thomas Agotnes, Guido Boella, Leon van der Torre, 2011-07-06 This book constitutes the proceedings of the 12th International Workshop on Computational Logic in Multi Agent Systems CLIMA XII held in Barcelona Spain in July 2011 The 22 papers presented were carefully reviewed and selected from 43 submissions The purpose of the CLIMA workshops is to provide a forum for discussing techniques based on computational logic for representing programming and reasoning about agents and multi agent systems in a formal way This volume features five thematic special sessions secrets and trust knowledge and beliefs logics for games and social choice cooperation logic and languages and norms and normative multi agent systems

Antiviral Agents S. Ren, 2001-06 The unfortunate appearance of AIDS the manifold problems with herpesviruses and other viruses attacking humans have led to an enormous dynamism of worldwide research and to an immense increase in the corresponding literature With this first Special Topic of the monograph series Progress in Drug Research the editor and the publishers undertake an effort to supply concise reviews on virus research especially on the development of new and future antiviral agents in some important and widespread viral diseases Latest Progress in Drug Research articles dealing with new chemotherapeutics for the treatment of the most threatening viral diseases are presented These very well received articles were upgraded and supplemented with new chapters to form this actual overview of the achievements in the respective fields of virus research This special volume contains six review articles covering the latest studies on the HIV and hepatitis C and B viruses

Programming Multi-Agent Systems Rafael H. Bordini, Mehdi Dastani, Amal El Fallah Seghrouchni, 2006-03-20 This book constitutes the thoroughly refereed post proceedings of the Third International Workshop on Programming Multi Agent Systems ProMAS 2005 held in Utrecht The Netherlands in July 2005 as an associated event of AAMAS 2005 the main international conference on autonomous agents and multi agent systems The 14 revised full papers presented together with 2 invited articles are organized in topical sections on multi agent techniques and issues multi agent programming and multi agent platforms and organization

Agent-Based Manufacturing S.M. Deen, 2013-04-17 Low volume high variety products like personalized cars or customized engines will be the key issues for manufacturing in the 21st century The necessary

control technology is based on the concept of holons which are the units of production and behave as autonomous and cooperative agents providing flexibility adaptability agility and dynamic reconfigurability This book presents the latest research results in agent based manufacturing as carried out by researchers in academia and industry within the international Holonic Manufacturing Systems project As this project was driven by industry the results presented here are of vital interest not just to researchers in agent technologies or distributed artificial intelligence but also to engineers and professionals in industry who have to respond to rapid changes and new demands in production Intelligent Agents III. Agent Theories, Architectures, and Languages Michael J. Wooldridge, Nick Jennings, 1997-01-22 Intelligent agents are computer systems that are capable of flexible autonomous action in dynamic typically multi agent domains Over the past few years the computer science community has begun to recognise that the technology of intelligent agents provides the key to solving a range of complex software application problems for which traditional software engineering tools and techniques offer no solution This book the third in a series represents the state of the art in the science of agent systems It is based on papers presented at the 3rd workshop on Agent Theories Architectures and Languages ATAL 96 held in conjunction with the European Conference on Artificial Intelligence ECAI 96 in Budapest Hungary in August 1996 It is essential reading for anyone interested in this vital new technology *New Challenges in Applied Intelligence Technologies* Radoslaw Katarzyniak, 2008-05-29 To built intelligent systems that can cope with real world problems we need to develop computational mechanisms able to deal with very large amounts of data generate complex plans schedules and resource allocation strategies re-plan their actions in real time provide user friendly communication for human device interactions and perform complex optimization problems In each of these tasks intelligence technologies play an important role providing designers and creators with effective and adequate computational models The field of intelligence technologies covers a variety of computational approaches that are often suggested and inspired by biological systems exhibiting functional richness and flexibility of their natural behavior This class of technologies consists of such important approaches as data mining algorithms neural networks genetic algorithms fuzzy and multi-valued logics rough sets agent oriented computation often integrated into complex hybrid solutions Intelligence technologies are used to build machines that can act and think like living systems solve problems in an autonomous way develop rich private knowledge bases and produce results not foreseen and programmed in a direct way by designers and creators *2023 International Conference on Marine Equipment & Technology and Sustainable Development* Desen Yang, 2023-08-01 This book contains original peer reviewed and selected research papers that were presented at the 2023 International Conference on Marine Equipment Technology and Sustainable Development which took place in Beijing China on April 1st 2023 The papers cover a range of topics including but not limited to the vision and goals of building a maritime community with a shared future marine machinery and transportation marine ecology environmental protection and conservation marine safety future ships and marine equipment marine engineering marine information and technology

maritime policy and global governance The papers included in this volume provide the latest findings on methodologies algorithms and applications in marine equipment and technology as well as sustainable development As a result this book is an invaluable resource for researchers engineers and university students who are interested in these fields Intelligent Decision Support Systems Miquel Sànchez-Marrè,2022-03-28 This book with invaluable contributions of Professor Franz Wotawa in chapters 5 and 7 presents the potential use and implementation of intelligent techniques in decision making processes involved in organizations and companies It provides a thorough analysis of decisions reviewing the classical decision theory and describing usual methods for modeling the decision process It describes the chronological evolution of Decision Support Systems DSS from early Management Information Systems until the appearance of Intelligent Decision Support Systems IDSS It explains the most commonly used intelligent techniques both data driven and model driven and illustrates the use of knowledge models in Decision Support through case studies The author pays special attention to the whole Data Science process which provides intelligent data driven models in IDSS The book describes main uncertainty models used in Artificial Intelligence to model inexactness covers recommender systems and reviews available development tools for inducing data driven models for using model driven methods and for aiding the development of Intelligent Decision Support Systems **ECAI 2000** European Coordinating Committee for Artificial Intelligence,2000 This volume covers the whole spectrum of artificial intelligence including knowledge representation automated reasoning constraint based reasoning machine learning autonomous agents human language technology planning vision and robotics and AI aspects of uncertainty and of creativity The book further includes contributions on innovative application All contributions are peer reviewed by an international Programme Committee *Intelligent Autonomous Systems 15* Marcus Strand,Rüdiger Dillmann,Emanuele Menegatti,Stefano Ghidoni,2018-12-31 This book presents the latest advances and research achievements in the fields of autonomous robots and intelligent systems presented at the IAS 15 conference held in Baden Baden Germany in June 2018 It brings together contributions from researchers engineers and practitioners from all over the world on the main trends of robotics navigation path planning robot vision human detection and robot design as well as a wide range of applications This installment of the conference reflects the rise of machine learning and deep learning in the robotics field as employed in a variety of applications and systems All contributions were selected using a rigorous peer review process to ensure their scientific quality The series of biennial IAS conferences was started in 1986 since then it has become an essential venue for the robotics community

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