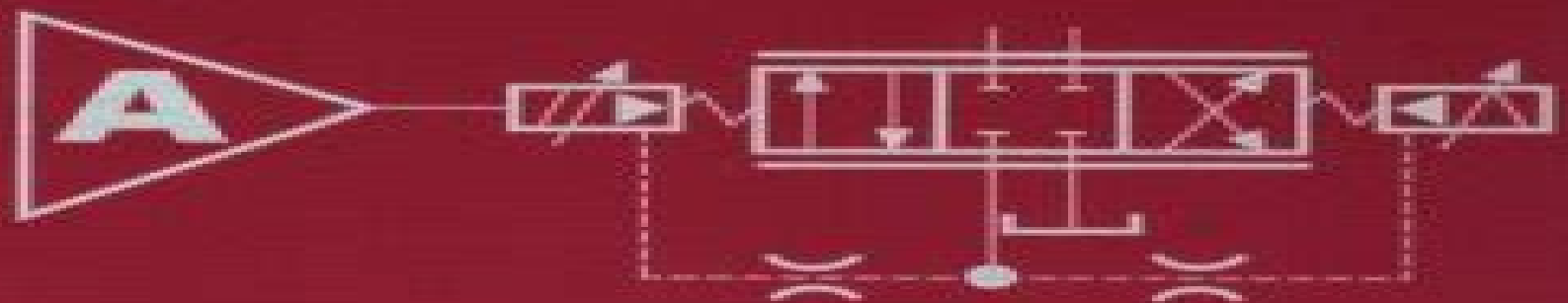


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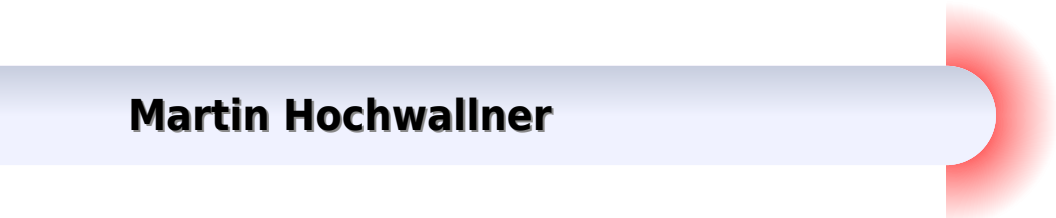
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Basic Electronics For Hydraulic Motion Control

Martin Hochwallner



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Design ,1997 Tradevman 1 & C. Naval Education and Training Program Development Center,1977 On Motion Control of Linear Incremental Hydraulic Actuators Martin Hochwallner,2017-10-24 Linear Incremental Hydraulic Actuators combine one or more short stroke cylinders and two or more engaging disengaging mechanisms into one actuator with long medium or even unlimited stroke length The motion of each single short stroke actuator concatenated by the engaging disengaging mechanisms forms the motion of the linear incremental hydraulic actuator The patterns of how these motions are concatenated form the gaits of a specific linear incremental hydraulic actuator Linear incremental hydraulic actuators may have more than one gait In an application the gaits may be combined to achieve optimal performance at various operating points The distinguishing characteristic of linear incremental hydraulic actuators is the incremental motion The term incremental actuator is seen as analogous to the incremental versus absolute position sensor Incremental actuators realize naturally relative positioning Incremental motion means also that the behavior does not depend on an absolute position but only on the relative position within a cycle or step Incremental actuators may realize discrete incremental or continuous incremental motion Discrete incremental actuators can only approach discrete positions whereby stepper drives are one prominent example In contrast continuous incremental actuators may approach any position Linear electric motors are one example of continuous incremental actuators The actuator has no inherent limitation in stroke length as every step or cycle adds only to the state at the beginning of the step or cycle and does not depend on the absolute position This led to the alternative working title Hydraulic Infinite Linear Actuator Linear incremental hydraulic actuator provides long stroke high force and linear motion and has the potential to decrease the necessary resource usage minimize environmental impact e g from potential oil spillage extend the range of feasible products longer stiffer better etc This thesis presents an analysis of the characteristics and properties of linear incremental hydraulic actuators as well as the gaits and possible realizations of some gaits The gait for continuous smooth motion with two cylinders is comprehensively studied and a control concept for the tracking problem is proposed The control concept encapsulates the complexity of the linear incremental hydraulic actuator so that an application does not have to deal with it One other gait the ballistic gait which realizes fast energy efficient motion enabling energy recuperation is studied **Understanding Automotive Electronics** William Ribbens,2012-12-31 Understanding Automotive Electronics is the first port of call for control engineers system engineers and electronic engineers in the automotive industry needing a thorough grounding in automotive electronics and control From simple automotive electronic circuits to the latest developments in telematics active safety entertainment and communications the book is also an ideal resource for more senior automotive engineers without a background in electronics or control needing to work in the area or supervise specialists Thoroughly updated throughout this new edition moves away from introductory mechanic level electronics to cover more hot topics such as transmission control hybrid control AUTOSAR AUTomotive Open System ARchitecture and vehicle networks Comprehensive coverage of automotive electronics and control

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